

M24 - 2 analogue outputs, M42 - 4 analogue outputs Programmable multi-transducer



for the measurement of electrical variables in heavy current power systems

Application

The RISH Ducer M42, M24 series of multi - transducers (Fig. 1) simultaneously measure several variables of an electric power system and process them to produce 2 resp. 2 or 3 Analogue outputs are available or power metering. For two of the limit outputs up to three misbrands can be logically combined.

The multi-transducers are also equipped with an RS 232 serial interface to which a PC with the corresponding software can be connected for programming or accessing and executing useful ancillary functions.

The usual modes of connection, the types of measured variables, their ratings. the transfer characteristic for each output etc. are the main parameters that have to be programmed.

Ancillary functions include a power system check, provision for displaying the measured variably on a PC monitor, the simulation of the outputs for test purposes and a facility for printing nameplates.

Features / Benefits

- Simultaneous measurement of several variables of a heavy-current power system / full supervision of an asymmetrically loaded four-wire power system ,rated current 1 to 6 A, rated voltage 57 to 400V (phase-to-neutral) or 100 to 693V (phase - to - phase)

Measured variables	Output	Types
Current ,Voltage (rms) , active/reactive/apparent power $\cos \phi$, $\sin \phi$, power factor RMS value of the current with wire setting range (bimetal measuring function)	2 analog output and 4digital outputs	RISHDucer M24
	Or 4 analogue pouts and 2 digital outputs	RISHDucer M42
Slave pointer function for the measurement of the RMS value IB Frequency	4 analogue outputs and bus RS 485 (MODBUS) See Data Sheet M 40	RISHDucer M40 *
Average value of the currents with sign of the active power (power system only)	Data bus (LON) See Data Sheet M 00	RISHDucer M 00 *

- For all heavy-current power system variables
- Up to 6 outputs (2A+4D or 4A+2D)
- Input voltage up to 693V (phase-to-phase)
- Universal analogue outputs (programmable)
- High accuracy: U/I 0.2% Frequency 0.15 % and P 0.25 % (under reference conditions)
- Universal digital outputs (meter transmitter, limits)
- Up to 2 or 4 integrated power meters.

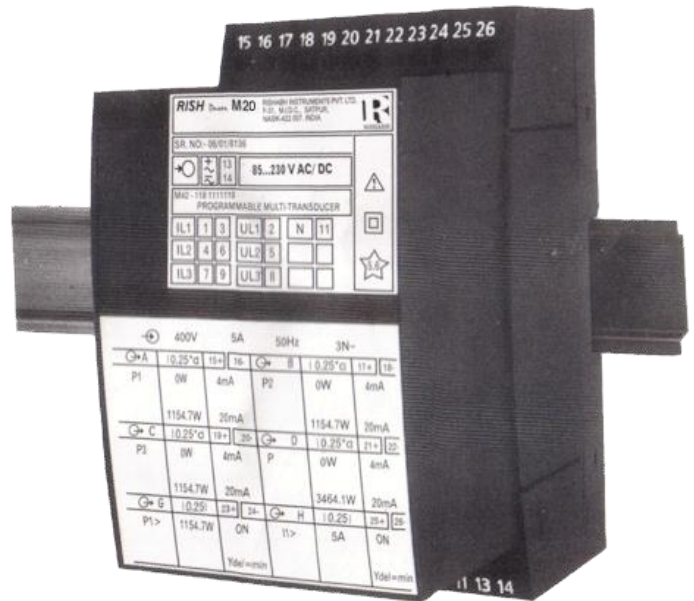
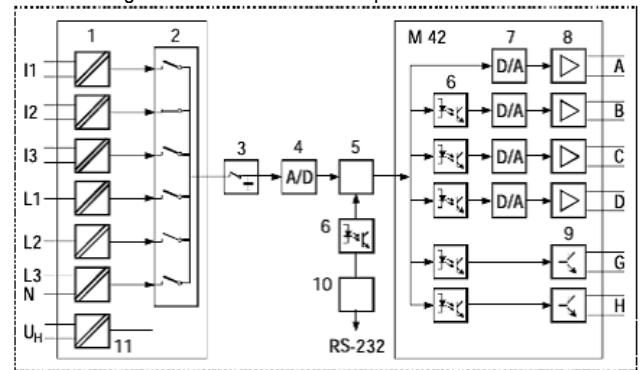


Fig.1.the universal basic version
RISHDucer M20, M30 in housing T24, clipped onto a top-hat rail.

- Windows software with password protection for programming, data analysis, power system status simulation, acquisition of meter data and making settings
- AC/DC power supply/universal
- Provision for either snapping the transducer onto top-hat rails or securing it with screws to a wall or panel



- 1 = Input transformer
- 2 = Multiplexer
- 3 = Latching stage
- 4 = A/D converter
- 5 = Microprocessor
- 6 = Electrical insulation
- 7 = D/A converter
- 8 = Output amplifier/latching stage
- 9 = Digital output (open-collector)
- 10 = Programming interface RS-232
- 11 = Power supply

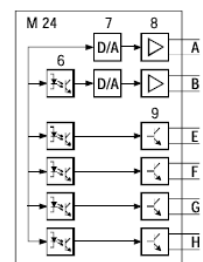


Fig.2.Block diagram.
A,B,C,D = analogue outputs; E,F,G,H = digital outputs

*Contact to factory for complete details

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Symbols

Symbols	Meaning	Symbols	Meaning
X	Measured variable	Q	Reactive power of the system $Q = Q_1 + Q_2 + Q_3$
X0	Lower limit of the measured variable	Q1	Reactive power phase 1 (phase-to-neutral L1 - N)
X1	Break point of the measured variable	Q2	Reactive power phase 2 (phase-to-neutral L2 - N)
X2	Upper limit of the measured variable	Q3	Reactive power phase 3 (phase-to-neutral L3 - N)
Y	Output variable	S	Apparent power of the system $S = \sqrt{I_1^2 + I_2^2 + I_3^2} \cdot \sqrt{U_1^2 + U_2^2 + U_3^2}$
Y0	Lower limit of the output variable	S1	Apparent power phase 1 (phase-to-neutral L1 - N)
Y1	Break point of the output variable	S2	Apparent power phase 2 (phase-to-neutral L2 - N)
Y2	Upper limit of the output variable	S3	Apparent power phase 3 (phase-to-neutral L3 - N)
U	Input voltage	Sr	Rated value of the apparent power of the system
Ur	Rated value of the input voltage	PF	Active power factor $\cos \phi = P/S$
U12	Phase-to-phase voltage L1 - L2	PF1	Active power factor phase 1 P_1/S_1
U23	Phase-to-phase voltage L2 - L3	PF2	Active power factor phase 2 P_2/S_2
U31	Phase-to-phase voltage L3 - L1	PF3	Active power factor phase 3 P_3/S_3
U1N	Phase-to-phase voltage L1 - N	QF	Reactive power factor $\sin \phi = Q/S$
U2N	Phase-to-phase voltage L2 - N	QF1	Reactive power factor phase 1 Q_1/S
U3N	Phase-to-phase voltage L3 - N	QF2	Reactive power factor phase 2 Q_2/S_2
UM	Average value of the voltages $(U_{1N} + U_{2N} + U_{3N}) / 3$	QF3	Reactive power factor phase 3 Q_3/S_3
I	Input current	LF	Power factor of the system $LF = \text{sgn } Q \cdot (1 - PF)$
I1	AC current L1	LF1	Power factor phase 1 $\text{sgn } Q_1 \cdot (1 - PF1)$
I2	AC current L2	LF2	Power factor phase 2 $\text{sgn } Q_2 \cdot (1 - PF2)$
I3	AC current L3	LF3	Power factor phase 3 $\text{sgn } Q_3 \cdot (1 - PF3)$
Ir	Rated value of the input current	C	Factor for the intrinsic error
IM	Average value of currents $(I_1 + I_2 + I_3) / 3$	R	Output load
IMS	Average value of the currents and sign of the active power (P)	Rn	Rated burden
IB	RMS value of the current with wire setting range (bimetal measuring function)	H	Power supply
IBT	Response time for IB	Hn	Rated value of the power supply
BS	Slave pointer function for the measurement of the RMS value IB	CT	c.t. ratio
BST	Response time for BS	VT	v.t. ratio
ϕ	Phase-shift between current and voltage		
F	Frequency of the input variable		
Fn	Rated frequency		
P	Active power of the system $P = P_1 + P_2 + P_3$		
P1	Active power phase 1 (phase-to-neutral L1 - N)		
P2	Active power phase 2 (phase-to-neutral L2 - N)		
P3	Active power phase 3 (phase-to-neutral L3 - N)		

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Applicable standards and regulations

DIN EN 60 688	Electrical measuring transducers for converting AC electrical variables into analogue and digital signals
IEC 1010 or EN 61 010	Safety regulations for electrical measuring, control and laboratory equipment
EN 60529	Protection types by case (code IP)
IEC 255-4 Part E5	High-frequency interference test (solid-state relays only)
IEC 1000-4-2,3,4,6	Electromagnetic compatibility for industrial process measurement and control equipment
VDI/VDE 3540 Page 2	Reliability of measuring and control equipment (classification of climates)
DIN 40 110	AC quantities
DIN 43 807	Terminal markings
IEC 68/2-6	Basic environmental testing procedures, vibration, sinusoidal
IEC 1036	Solid state AC watt hour meters for active power (Classes 1 and 2)
DIN 43864	Current interface for the transmission of impulses between impulse encoder counter and tariff meter
UL 94	Tests for flammability of plastic materials for parts in devices and appliances

Technical data

Inputs

Input variables:	see Table 2 and 3
Measuring ranges:	see Table 2 and 3
Waveform:	Sinusoidal
Rated frequency:	50...60 Hz; 16 2/3 Hz
Consumption:	Voltage circuit: $\leq U^2 / 400 \text{ kW}$ Condition external power supply Current circuit: $0.3 \text{ VA} \cdot I/5 \text{ A}$

Continuous thermal ratings of inputs

Current circuit	10 A 400V single-phase AC system 693 V three-phase system
Voltage circuit	480 V single-phase AC system 831 V three-phase system

Short-time thermal rating of inputs

Input variable	Number of inputs	Duration of overload	Interval between two overloads
Current circuit	400 V single-phase AC system 693 V three-phase system		
100 A	5	3 S	5 min.
250 A	1	1 S	1 hour
Voltage circuit	1 A, 2 A, 5 A		
Single-phase AC system 600 V $H_{\text{intern}}: 1.5 U_r$	10	10 S	10 S
Three-phase system 1040 V $H_{\text{intern}}: 1.5 U_r$	10	10 S	10 S

Analogue outputs For the outputs A,B,C,D

Output variable Y	Impressed DC current	Impressed DC voltage
Full scale Y2	see "Ordering Information"	see "Ordering Information"
Limits of output signal for input overload and/or		
$R = 0$	$1.25 \cdot Y2$	40 mA
$R \rightarrow \infty$	30V	$1.25 Y2$
Rated useful range of output load	$0 \leq \frac{7.5 \text{ V}}{Y2} \leq \frac{5 \text{ V}}{Y2}$	$\frac{Y2}{2\text{mA}} \leq \frac{Y2}{1\text{mA}} \leq \infty$
AC component of output signal (peak-to-peak)	$\leq 0.005 Y2$	$\leq 0.005 Y2$

The outputs A,B,C may be either short or open-circuited. They are electrically insulated from each other and from all other circuits (floating)

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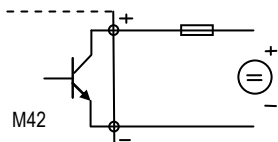
All the full-scale output values can be reduced subsequently using the programming software, but a supplementary error results.

The hardware full-scale settings for the analogue outputs may also be changed subsequently. Conversion of a current to a voltage output or vice is also possible. This necessitates changing resistors on the output board. The full-scale values of the current and voltage outputs are set by varying the effective value of two parallel resistors (better resolution). The values of the resistors are selected to achieve the minimum absolute error. Calibration with the programming software is always necessary following conversion of the outputs. Refer to the Operating instructions. caution: The warranty is void if the device is tampered with

Digital outputs, pulse outputs, limit outputs → ○

The digital outputs conform to DIN 43 864. The pulse width can be neither programmed nor is there a hardware setting.

- Type of contact: Open collector
- Number of pulses: see "Ordering information"
- Pulse duration: ≥ 100 ms
- Interval: ≥ 100 ms
- Power supply: 8...40V
- Output current: ON 10 ...27 mA
OFF ≤ 2 mA



Reference conditions

- Ambient temperature: $+ 23 \text{ }^\circ\text{C} \pm 1\text{K}$
- Pre-conditioning: 30 min. acc. to DIN EN 60 688 Section 4.3, Table 2
- Input variable: Rated useful range
- Power supply: $H = H_n \pm 1\%$
- Active/reactive factor: $\cos \varphi = 1$ resp. $\sin \varphi = 1$
- Frequency: 50...60 Hz, 16 2/3 Hz
- Waveform: Sinusoidal, form factor 1.1107
- Output load: DC current output:
 $R_n = \frac{7.5 \text{ V}}{Y_2} \pm 1\%$
DC voltage output:
 $R_n = \frac{Y_2}{1 \text{ mA}} \pm 1\%$
- Miscellaneous: DIN EN 60 688

System response

Accuracy class: (the reference value is the full-scale value Y2)

Measured variables	Condition	Accuracy class*
System: Active, reactive and apparent power	$0.5 \leq X_2/S_r \leq 1.5$ $0.3 \leq X_2/S_r < 0.5$	0.25 c 0.5 c
Phase: Active, reactive and apparent power	$0.167 \leq X_2/S_r \leq 0.5$ $0.1 \leq X_2/S_r < 0.167$	0.25 c 0.5 c
Power factor active, reactive and apparent power	$0.5 S_r \leq S \leq 1.5 S_r$ $(X_2 - X_0) = 2$	0.25 c
	$0.5 S_r \leq S \leq 1.5 S_r$ $1 \leq (X_2 - X_0) < 2$	0.5 c
	$0.5 S_r \leq S \leq 1.5 S_r$ $0.5 \leq (X_2 - X_0) < 1$	1.0 c
	$0.1 S_r \leq S < 0.5 S_r$ $(X_2 - X_0) = 2$	0.5 c
	$0.1 S_r \leq S < 0.5 S_r$ $1 \leq (X_2 - X_0) < 2$	1.0 c
	$0.1 S_r \leq S < 0.5 S_r$ $0.5 \leq (X_2 - X_0) < 1$	2.0 c
AC voltage	$0.1 U_r \leq U \leq 1.2 U_r$	0.2 c
AC current/ current averages	$0.1 I_r \leq I \leq 1.5 I_r$	0.2 c
System frequency	$0.1 U_r \leq U \leq 1.2 U_r$ resp. $0.1 I_r \leq I \leq 1.5 I_r$	$0.15 + 0.03 \text{ c}$ ($f_N = 50 \dots 60 \text{ Hz}$) $0.15 + 0.1 \text{ c}$ ($f_N = 16 \text{ 2/3 Hz}$)
	Pulse	acc. to IEC 1036 $0.1 I_r \leq I \leq 1.5 I_r$

*Basic accuracy 0.5 c for applications with phase-shift

Duration of the measurement cycle: Approx. 0.25 to 0.5 s at 50 Hz depending on measured variable and programming

Response time: 1...2 times the measurement cycle
Factor c (the highest value applies):

Linear characteristic:	$C = \frac{1 - \frac{Y_0}{Y_2}}{1 - \frac{X_0}{X_2}}$ or $C = 1$
Bent characteristic: $X_0 \leq X \leq X_1$	$C = \frac{Y_1 - Y_0}{X_1 - X_0} \cdot \frac{X_2}{Y_2}$ or $C = 1$
$X_1 < X \leq X_2$	$C = \frac{\frac{Y_1}{Y_2}}{\frac{X_1}{X_2}}$ or $C = 1$

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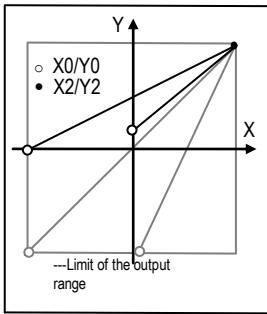


Fig. 3 Examples of settings with linear characteristic

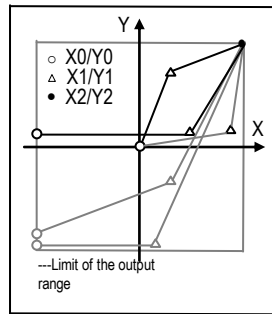


Fig. 4 Examples of settings with bent characteristic.

Influencing quantities and permissible variations

Acc. to DIN IEC 688

Safety

Protection class:	II		
Enclosure protection:	IP 40, housing IP 20, terminals		
Overvoltage category:	III		
Insulation test (versus earth):	Input voltage:	AC	400V
	Input current:	AC	400V
	Output:	DC	40V
	Power supply:	AC	400V
		DC	230V

Surge test:	5 kV; 1.2/50 us; 0.5 Ws		
Test voltages:	50 Hz, 1 Min. according to DIN EN 61 010-1		
	5550 V inputs versus all other circuits as well as outer surface		
	3250 V input circuits versus each other		
	3700 V power supply versus outputs and SCI as well as outer surface		
	490 V outputs and SCI versus each other and versus outer surface		

Power supply → ○

AC voltage	100, 110, 230, 400, 500, or 693 V
	±10%, 45 to 65 Hz
	Power consumption approx. 10 VA

AC/DC power pack (DC and 50... 60 Hz)

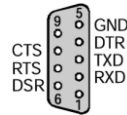
Table 1: Rated voltages and tolerances

Rated voltage U_N	Tolerance
24...60V DC/AC	DC - 15...+ 33%
85...230V DC/AC	AC ± 10%

Consumption: ≤ 9 W resp. ≤ 10 VA

Programming connector on transducer

Interface:	RS 232 C
DSUB socket:	9-pin



The interface is electrically insulated from all other circuits

Installation data

Housing:	Housing T24 See Section "Dimensioned drawings"
Housing material:	Lexan 940 (Polycarbonate). Flammability class V-0 acc. to UL 94 self-extinguishing, non-dripping, free of halogen
Mounting:	For snapping onto top-hat rail (35 X 15 mm or 35 X 7.5 mm) acc. to EN 50 022 or directly onto a wall or panel using the pull-out screw hole brackets
Orientation:	Any
Weight:	With supply transformer approx. 1.1 kg With AC/DC power pack approx. 0.7 kg

Terminals

Type:	Screw terminals with wire guards
Max. wire gauge:	≤ 4.0 mm ² single wire or 2 X 2.5 mm ² fine wire

Vibration withstand

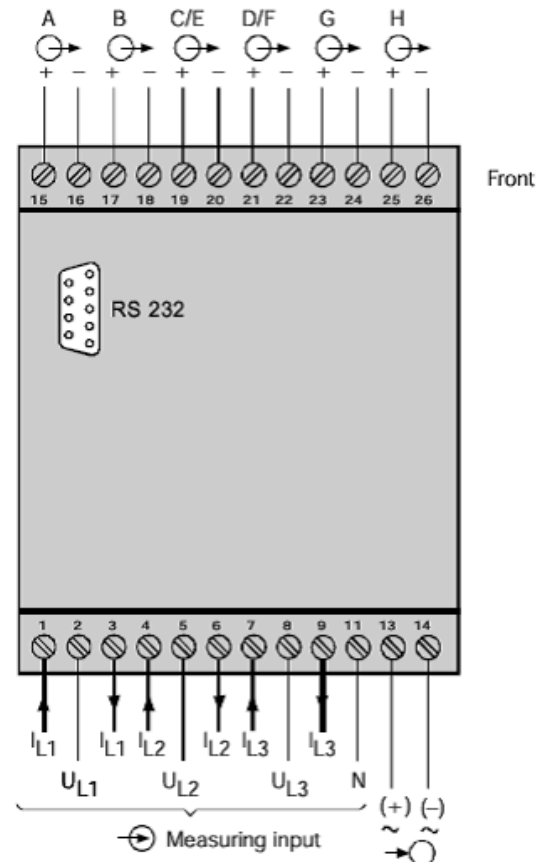
(tested according to DIN EN 60 068-2 -6)	
Acceleration:	± 2 g
Frequency range:	10...150...10 Hz, rate of frequency sweep: 1 octave/minute
Number of cycles:	10 in each of the three axes
Result:	No faults occurred, no loss of accuracy and no problems with the snap fastener

Ambient conditions

Climatic rating:	Climate class 3 acc. to VDI/VDE 3540
Variations due to ambient temperature:	± 0.1%/10 K
Nominal range of use for temperature:	0...15...30...45 °C (usage group II)
Storage temperature:	- 40 to + 85 °C
Annual mean relative humidity:	≤ 75%

Electrical connections

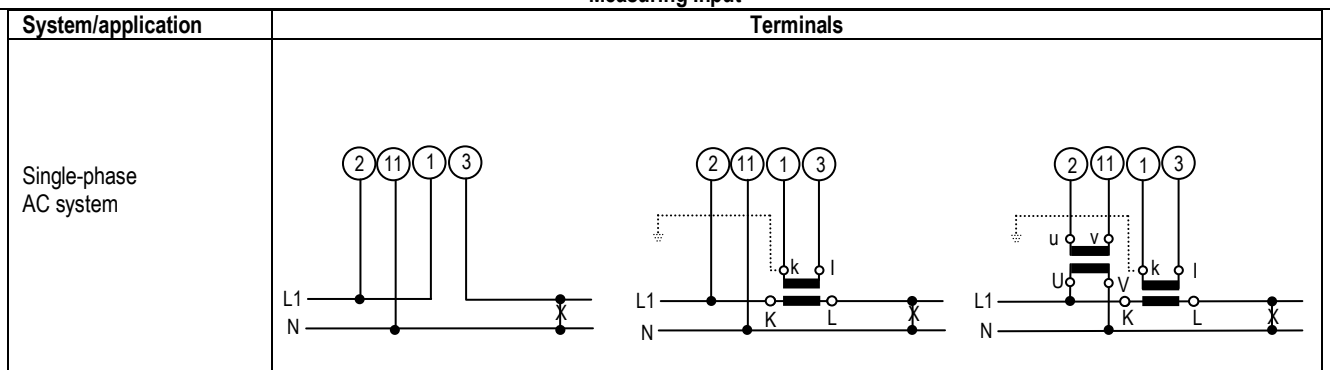
Function			Connection		
Meas. input 	AC current	IL1	1 / 3		
		IL2	4 / 6		
		IL3	7 / 9		
	AC voltage	UL1	2		
		UL2	5		
		UL3	8		
Outputs 	Analogue	Digital	N	11	
	A	+	-	15	
				16	
		B	+	-	17
					18
	C	+	-	19	
				20	
	D	+	-	21	
				22	
	G	+	-	23	
				24	
	H	+	-	25	
				26	
Power supply AC 	~	~	13		
			14		
	DC	+	-	13	
				14	



If power supply is taken from the measured voltage internal connections are as follow.:

Application (system)	Internal connection Terminal / System
Single phase AC current	2 / 11 (L1 - N)
4-wire 3-phase symmetric load	2 / 11 (L1 - 2)
All other*	2 / 5 (L1 - L2)

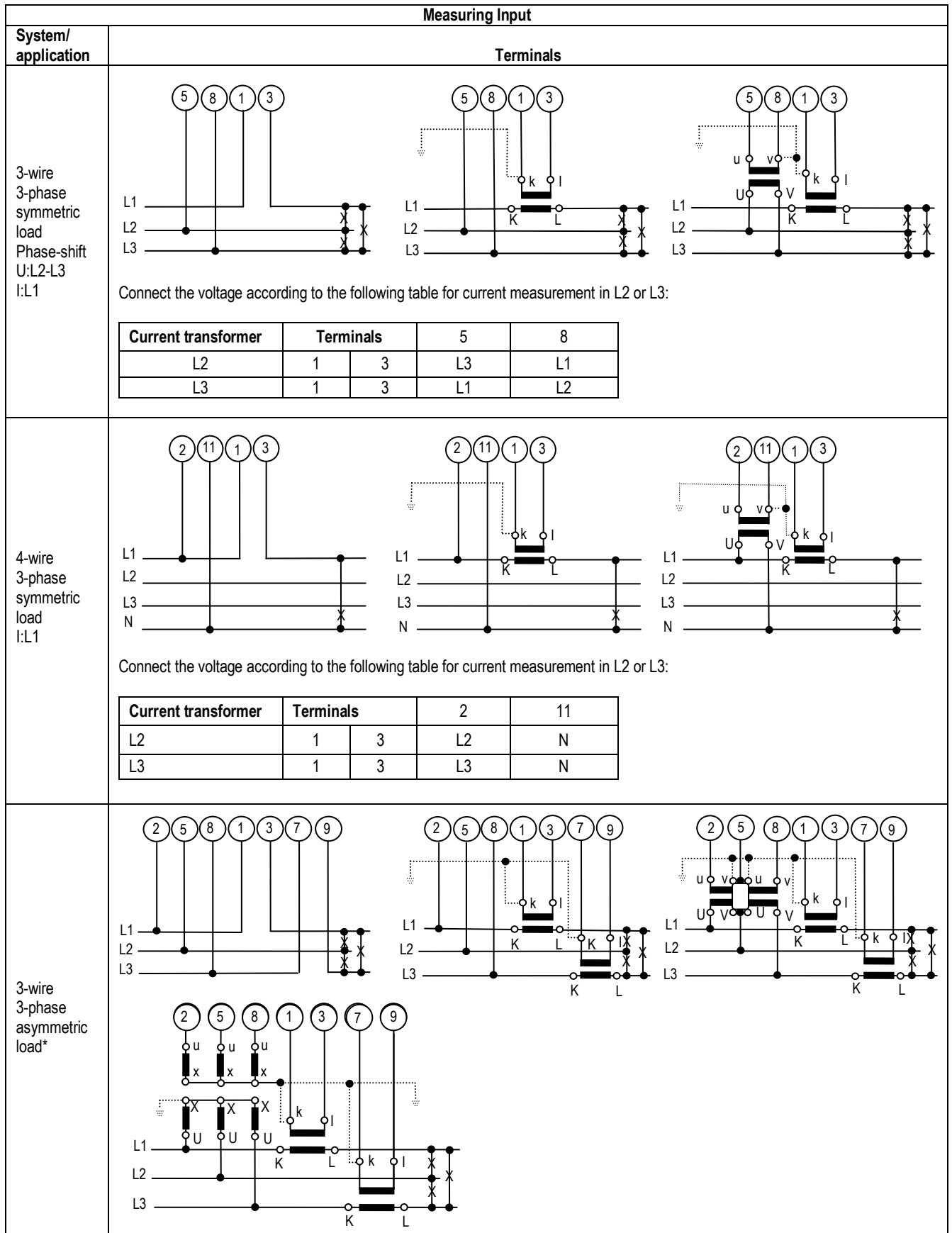
Measuring Input



*Contact to factory for complete details

Measuring Input																
System/ application	Terminals															
3-wire 3-phase symmetric load I:L1	<p>Connect the voltage according to the following table for current measurement in L2 or L3:</p> <table border="1"> <thead> <tr> <th>Current transformer</th> <th>Terminals</th> <th>2</th> <th>5</th> <th>8</th> </tr> </thead> <tbody> <tr> <td>L2</td> <td>1 3</td> <td>L2</td> <td>L3</td> <td>L1</td> </tr> <tr> <td>L3</td> <td>1 3</td> <td>L3</td> <td>L1</td> <td>L2</td> </tr> </tbody> </table>	Current transformer	Terminals	2	5	8	L2	1 3	L2	L3	L1	L3	1 3	L3	L1	L2
Current transformer	Terminals	2	5	8												
L2	1 3	L2	L3	L1												
L3	1 3	L3	L1	L2												
3-wire 3-phase symmetric load Phase-shift U:L1 - L2 I:L1	<p>Connect the voltage according to the following table for current measurement in L2 or L3:</p> <table border="1"> <thead> <tr> <th>Current transformer</th> <th>Terminals</th> <th>2</th> <th>5</th> </tr> </thead> <tbody> <tr> <td>L2</td> <td>1 3</td> <td>L2</td> <td>L3</td> </tr> <tr> <td>L3</td> <td>1 3</td> <td>L3</td> <td>L1</td> </tr> </tbody> </table>	Current transformer	Terminals	2	5	L2	1 3	L2	L3	L3	1 3	L3	L1			
Current transformer	Terminals	2	5													
L2	1 3	L2	L3													
L3	1 3	L3	L1													
3-wire 3-phase symmetric Load Phase-shift U:L3 - L1 I:L1	<p>Connect the voltage according to the following table for current measurement in L2 or L3:</p> <table border="1"> <thead> <tr> <th>Current transformer</th> <th>Terminals</th> <th>8</th> <th>2</th> </tr> </thead> <tbody> <tr> <td>L2</td> <td>1 3</td> <td>L1</td> <td>L2</td> </tr> <tr> <td>L3</td> <td>1 3</td> <td>L2</td> <td>L3</td> </tr> </tbody> </table>	Current transformer	Terminals	8	2	L2	1 3	L1	L2	L3	1 3	L2	L3			
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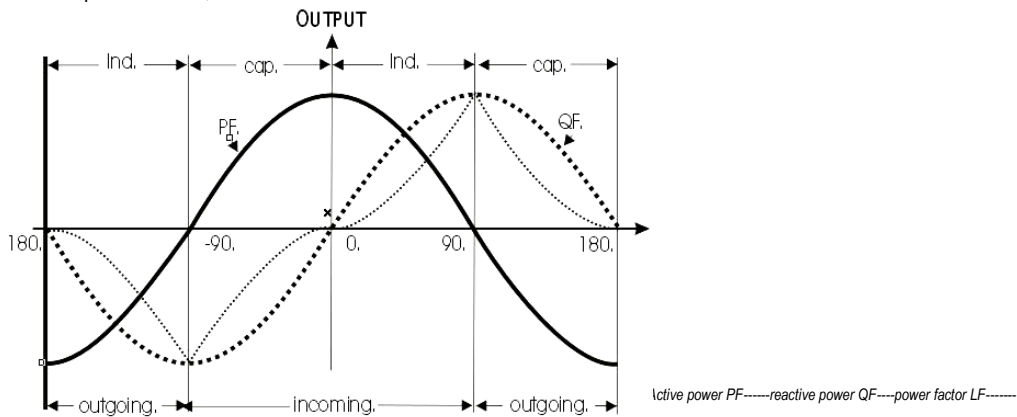
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Measuring Input		
System/ application	Terminals	
4-wire 3-phase asymmetric load*		
		<p>3 single-pole insulated voltage transformers in high-voltage system</p>
4-wire 3-phase asymmetric load* Open Y connection*	<p>Low-voltage system</p>	<p>2 single-pole insulated voltage transformers In high-voltage system</p>

*Contact to factory for complete details

Relationship between PF, QF and LF



RISH DucerM42, M24

Programmable multi-transducer

Table 2:RishDucer M20, M30, standard version

The two versions of the transducer below with the basic programming are available AC Aux.& AC/DC Aux.

Description / Basic programming		M42	M24
Mechanical design: Rated frequency:	Housing T24 for rail and wall mounting 50 Hz (60 Hz admissible without additional error re-programming by user for user for 16 2/3Hz possible, but with additional error 1.25 C)	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>
Power supply:	230V AC 85...230V DC/AC	<input type="checkbox"/> <input type="checkbox"/>	<input type="checkbox"/> <input type="checkbox"/>
Power supply:	External connection (standard)	<input type="checkbox"/>	<input type="checkbox"/>
Full-scale output signal, output A:	Y2 = 20mA	<input type="checkbox"/>	<input type="checkbox"/>
Full-scale output signal, output B:	Y2 = 20mA	<input type="checkbox"/>	<input type="checkbox"/>
Full-scale output signal, output C:	Y2 = 20mA	<input type="checkbox"/>	N.A
Full-scale output signal, output D:	Y2 = 20mA	<input type="checkbox"/>	N.A
Test certificate:	None supplied	<input type="checkbox"/>	<input type="checkbox"/>
Programming:	Basic	<input type="checkbox"/>	<input type="checkbox"/>
See Table 3: "Ordering information for RISHDucerM20, M30 models"			
Basle programming			
Application:	4-wire, 3-phase system, asymmetric load (NPS)	<input type="checkbox"/>	
Input voltage:	Design value $U_r = 400V$	<input type="checkbox"/>	
Input current:	Design value $I_r = 5A$ Without specification of primary ratings	<input type="checkbox"/>	
Measured variable, output A: Output signal, output A:	P1; X0 = 115.47 W; X2 = 115.47W # DC current Y0 = -20mA; Y2 = 20mA Linear characteristic Standard limits	<input type="checkbox"/>	<input type="checkbox"/>
Measured variable, output B: Output signal, output B:	P2; X0 = -115.47; X2 = 115.47W # DC current Y0 = -20mA; Y2 = 20mA Linear characteristic Standard limits	<input type="checkbox"/>	<input type="checkbox"/>
Measured variable, output C: Output signal, output C:	P3; X0 = 115.47 W; X2 = 115.47W # DC current Y0 = 20mA; Y2 = 20mA Linear characteristic Standard limits	<input type="checkbox"/>	N.A
Measured variable, output D: Output signal, output D:	P:X0= -346.41; x2 = 346.41W # DC current Y0 = -20 mA; Y2 = 20 mA Linear characteristic Standard limits	<input type="checkbox"/>	N.A
Measured variable, output E:	Limit P; X1 = 311.77 W # Output ON if X>X1 Min.Pick-up delay	N.A	<input type="checkbox"/>
Measured variable, output F:	Limit Q; X1 = 34.64 var # Output ON if X>X1 Min.pick-up delay	<input type="checkbox"/>	<input type="checkbox"/>
Measured variable, output G:	Limit P1; X1 = 115.47 W # Output ON if X>X1 Min.pick-up delay	<input type="checkbox"/>	<input type="checkbox"/>
Measured variable, output H:	Limit I1; X1 = 2 A # Output ON if X>X1 Min.pick-up delay	<input type="checkbox"/>	<input type="checkbox"/>

#other specifications on request contact to Factory

RISH DucerM42, M24

Programmable multi-transducer

Table 3: Ordering information for RishDucer M20, M30 models
(see also Table 2: Standard version)

DESCRIPTION	M20	M30
1. Specify the type of system (1 phase, 3 phase 3 wire / 3 phase 4 wire / balanced / unbalanced etc.) C.T. / P.T Ratio	<input type="checkbox"/>	<input type="checkbox"/>
2. Rated frequency		
1) 50 Hz (60 Hz possible without additional error; 16 2/3 Hz additional error 1.25 • c)	<input type="checkbox"/>	
2) 60 Hz (50 Hz possible without additional error; 16 2/3 Hz additional error 1.25 • c)	<input type="checkbox"/>	
3) 16 2/3 Hz (not re-programming by user, 50/60 Hz possible, but with additional error 1.25 • c)	<input type="checkbox"/>	
3. Power supply Nominal range		
1) AC 90...110V H _n = 100V	<input type="checkbox"/>	
2) AC 99...121V H _n = 110V	<input type="checkbox"/>	
3) AC 207...253V H _n = 230V	<input type="checkbox"/>	
4) AC 360...440V H _n = 400V	<input type="checkbox"/>	
5) AC 450...550V H _n = 500V	<input type="checkbox"/>	
6) AC 623...762V H _n = 693V	<input type="checkbox"/>	
7) DC/AC 24...60V	<input type="checkbox"/>	
8) DC/AC 85...230V	<input type="checkbox"/>	
4. Power supply connection		
1) External (standard)	<input type="checkbox"/>	
2) Internal from voltage input**	<input type="checkbox"/>	
Line 2: Not available for rated frequency 16 2/3 Hz Contact Factory for further details		
5. Full-scale output signal, output A		
1) Output A, Y2 = 20mA (standard)	<input type="checkbox"/>	<input type="checkbox"/>
9) Output A, Y2 [mA]	<input type="checkbox"/>	<input type="checkbox"/>
Z) Output A, Y2 [V]	<input type="checkbox"/>	<input type="checkbox"/>
Line 9: Full-scale current Y2 [mA] 1 to 20 Line Z: Full-scale current Y2 [mA] 1 to 10		
6. Full-scale output signal, output B		
1) Output B, Y2 = 20mA (standard)	<input type="checkbox"/>	<input type="checkbox"/>
9) Output B, Y2 [mA]	<input type="checkbox"/>	<input type="checkbox"/>
Z) Output B, Y2 [V]	<input type="checkbox"/>	<input type="checkbox"/>
7. Full-scale output signal, output C		
1) Output C, = Y2 mA (standard)	N.A.	<input type="checkbox"/>
9) Output C, = Y2 [mA]	N.A.	<input type="checkbox"/>
Z) Output C, = Y2 [V]	N.A.	<input type="checkbox"/>
8. Full-scale output signal, output D		
2) Output D, = Y2 mA (standard)		<input type="checkbox"/>
9) Output D, = Y2 [mA]		<input type="checkbox"/>
Z) Output D, = Y2 [V]		
9. Digital Output E		
Specify output i) Limit control or	N.A.	<input type="checkbox"/>
ii) Pulse output	N.A.	<input type="checkbox"/>
Also specify the parameter and their details separately		
10. Digital Output F		
Specify output i) Limit control or	N.A.	<input type="checkbox"/>
ii) Pulse output	N.A.	<input type="checkbox"/>
Also specify the parameter and their details separately		
11. Digital Output G		
Specify output i) Limit control or	<input type="checkbox"/>	<input type="checkbox"/>
ii) Pulse output	<input type="checkbox"/>	<input type="checkbox"/>
Also specify the parameter and their details separately		

*Specify separately

**Contact Factory for complete details

M24 - 2 analogue outputs, M42 - 4 analogue outputs Programmable multi-transducer

DESCRIPON	M 42	M 24
12. Digital Output H		
Specify output i) Limit control or	N.A.	<input type="checkbox"/>
ii) Pulse output	N.A.	<input type="checkbox"/>
Also specify the parameter and their details separately		
13. Test certificate		
0) None supplied	N.A.	<input type="checkbox"/>
1) Supplied	N.A.	<input type="checkbox"/>
14. Programming		
0) Basic	<input type="checkbox"/>	<input type="checkbox"/>
1) According to specification	<input type="checkbox"/>	<input type="checkbox"/>
Line 0: Not available if the power supply is taken from the voltage input		

Dimensioned drawings

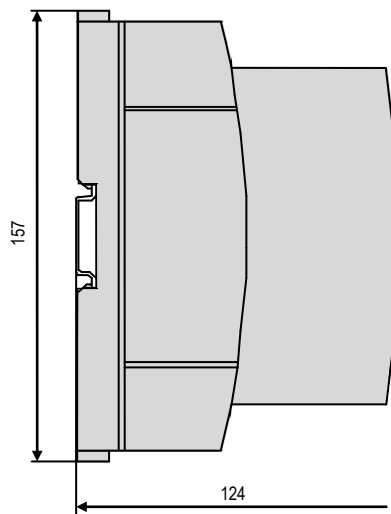
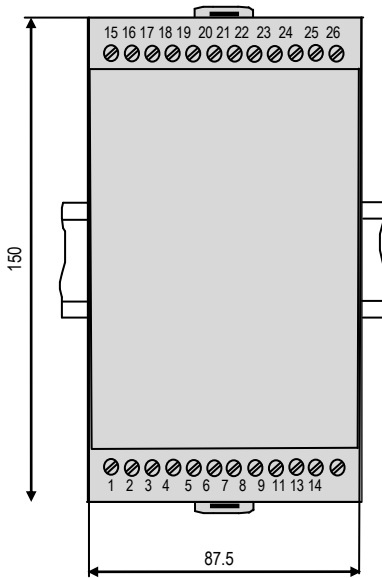


Table 4: Accessories

Description
Programming cable
PC software RISH Durer (in English on two 3 1/2* discs)
Operating Instructions RISH Ducer M20, M30. in English

Fig.6 RISHDucer M20, M30 in housing
(35 15 mm or 35 7.5 mm, acc. to EN 50 022).

T24 clipped onto a top-hat rail

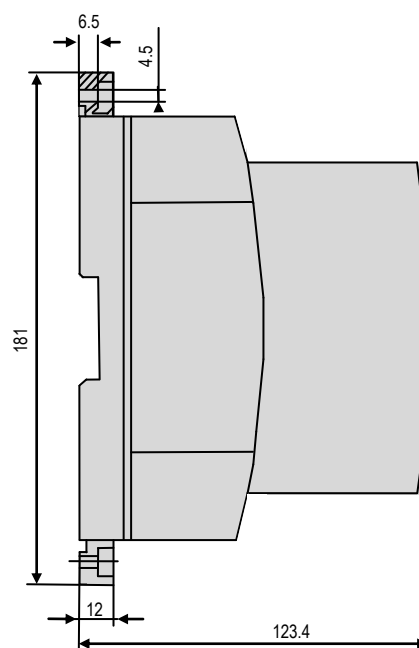
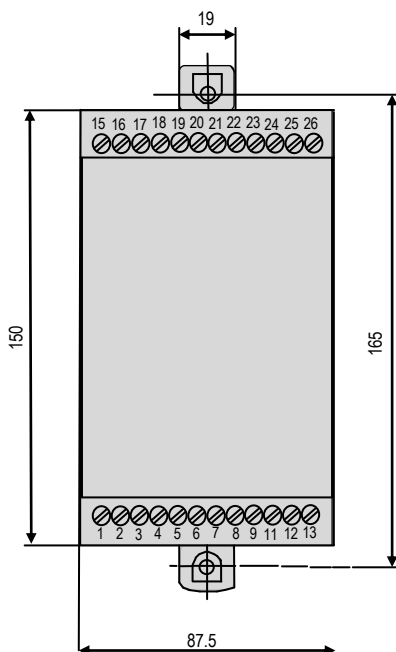


Fig.7. RISH Ducer M20, M30 in housing
Brackets pulled out.

T24, screw hole mounting