RISH Ducer V 604 Programmable universal transmitter

for DC currents or voltages, temperature sensors, remote sensors or potentiometers

Fig.1

Fig.2

Fig. 1. Transmitter RISHDucer V 604 in housing S17 Clipped on to a top-hat rail

Fig. 2. Transmitter RISHDucer V 604 in housing S17 screw hole Mounting brackets pulled out.

Application

The universal transmitter *RISH* Ducer V 604 (Figures 1 and 2) convert the input variable – a DC current or voltage, or a signal from a thermocouple, resistance thermometer, remote sensor or potentiometer – to a proportional analogue output signal.

The analogue output signal is either an impressed current or superimposed voltage which is processed by other devices for purposes of displaying, recording and/or regulating a constant.

A considerable number of measuring ranges including bipolar or spread ranges are available.

Input variable and measuring range are programmed with the aid of a PC and the corresponding software. Other parameters relating to specific input variable data, the analogue output signal, the transmission mode, the operating sense and the open-circuit sensor supervision can also be programmed.

The open-circuit sensor supervision is in operation when the *Rish* Ducer V 604 is used in conjunction with a thermocouple, resistance thermometer, remote sensor or potentiometer.

The transmitter fulfils all the important requirements and regulations concerning electromagnetic compatibility EMC and Safety (IEC 1010 resp. EN 61 010). It was developed and is manufactured and tested in strict accordance with the quality assurance standard ISO 9001.

Production QA is also certified according to guideline 94/9/EG.

Features / Benefits

- **Input variable** (temperature, variation of resistance, DC signal) **and measuring range programmed using PC / Simplifies project planning and engineering** (the final measuring range can be determined during commissioning). **Short delivery times and low stocking levels**
- **Analogue output signal also programmed on the PC** (impressed current or superimposed voltage fo r all ranges between – 20 and + 20 mA DC resp. – 12 and + 15 V DC) / **Universally applicable. Short delivery times and low stocking levels**
- **Electric insulation between measured variable, analogue output signal and power supply / Safe isolation acc. to EN 61 010**
- **Wide power supply tolerance / Only two operating voltage ranges between 20 and a maximum of 264 V DC/AC**
- Standard Version as per Germanischer Lloyd
- **Provision for either snapping the transmitter onto top-hat rails or securing it with screws to a wall or panel**
- **Housing only 17.5 mm wide (size S17 housing) / Low space requirement**
- **Other programmable parameters: specific measured variable data** (e.g. two, three or four-wire connection for resistance thermometers, “internal” or “external” cold junction compensation of thermocouples etc,.)**transmission mode** (special linearised characteristic or characteristic determined by a mathematical relationship, e.g. output signal = f (measured variable)), **operating sense** (output signal directly or inversely proportional to the measured variable)**and open-circuit sensor supervision** (output signal assumes fixed preset value between – 10 and 110%, supplementary output contact signaling relay) / **Highly flexible solutions for measurement problems**
- **All programming operations by IBM XT, AT or compatible PC running the self- explanatory, menu-controlled programming software, if necessary, during operation / No ancillary hand-held terminals needed**
- **Digital measured variable data available at the programming interface/ Simplifies commissioning, measured variable and signals can be viewed on PC in the field**
- **Standard software includes functional test program / No external simulator or signal injection necessary**
- **Self-monitoring function and continuously running test program / Automatic signaling of defects and device failure**

Principle of operation (Fig. 3)

The measured variable M is stepped down to a voltage between –300 and 300 mV in the input stage (1).The input stage includes potential dividers and shunts for this purpose. A constant reference current facilitates the measurement of resistance. Depending on the type of measurement, either one or more of the terminals 1, 2, 6, 7 and 12 and the common ground terminal 11 are used.

The constant reference current which is needed to convert a variation of resistance such as that of a resistance thermometer, remote sensor or potentiometer to a voltage signal is available at terminal 6. The internal current source (2) automatically sets the reference current to either 60 or 380 μA to suit the measuring range. The corresponding signal is applied to terminal 1 and is used for resistance measurement.

Terminal 2 is used for “active” sensors, i.e. thermocouples or other mV generators which inject a voltage between –300 and 300 mV. Small currents from the open-circuit sensor supervision (3) are superimposed on the signals at terminals 1 and 2 in order to monitor the continuity of the measurement circuit. Terminal 2 is also connected to the cold junction compensation element which is a Ni 100 resistor built into the terminal block.

Terminals 7 and 12 are also input terminals and are used for measuring currents and for voltages which exceed 300 mV.

An extremely important component of the input stage is the EMC filter which protects the transmitter from interference or even destruction due to induced electromagnetic waves.

From the input stage,the measured variable(e.g.the voltage of a thermocouple) and the two auxiliary signals (cold junction compensation and the open-circuit sensor supervision) go to the multiplexer (4), which controlled by the micro-controller (6) applies them cyclically to the A/D converter (5).

The A/D converter operates according to the dual slope principle with an integration time of 20 ms at 50 Hz and a conversion time of approximately 38 ms per cycle. The internal resolution is 12 Bit regardless of measuring range.

The micro-controller relates the measured variable to the auxiliary signals and to the data which were loaded in the micro-controller’s EEPROM via the programming connector (7) when the transmitter was configured. These settings determine the type of measured variable, the measuring range, the transmission mode (e.g. linearised temperature/thermocouple voltage relationship) and the operating sense (output signal directly or inversely proportional to the measured variable). The measured signal is then filtered again, but this time digitally to achieve the maximum possible immunity to interference. Finally the value of the measured variable for the output signal is computed. Apart from normal operation, the programming connector is also used to transfer measured variables on-line from the transmitter to the PC or vice versa. This is especially useful during commissioning and maintenance

Depending on the measured variable and the input circuit, it can take 0.4 to 1.1 seconds before a valid signal arrives at the opt coupler (8). The different processing times result from the fact that, for example, a temperature measurement with four-wire resistance thermometer and open-circuit sensor supervision requires more measuring cy a low voltage. clews than the straight forward measurement of a low voltage.

The main purpose of the opts-coupler is to provide electrical insulation between input and output. On the output side of the opt coupler, the D/A converter (9) transforms the digital signal back to an analogue signal which is then amplified in the output stage (10) and split into two non-electrically isolated output channels. A powerful heavy-duty output is available at A1 and a less powerful output for a field display unit at A2. By a combination of programming and setting the 8 DIP switches in the output stage, the signals at A1 and A2 can be configured to be either a DC current or DC voltage (but both must be either one or the other). The signal A1 is available at terminals 9 and 4 and A2 at terminals 8 and 3.

If the micro-controller (6) detects an open-circuit measurement sensor, it firstly sets the two output signals A1 and A2 to a constant value. The latter can be programmed to adopt a preset value between –10 and 110% or to maintain the value it had at the instant the open-circuit was detected. In this state, the micro-controller also switches on the red LED (11) and causes the green LED (12) to flash. Via the opts-coupler (8), it also excites the relay driver (13) which depending on configuration switches the relay (14) to its energized or de-energized state. The output contact is available at terminals 13, 14 and 15. It is used by safety circuits. In addition to being able to program the relay to be either energized or de-energized, it can also be set to "relay disabled". In this case, an open circuit sensor is only signaled by the output signal being held constant, the red LED being switched on and the green LED flashing. The relay can also be configured to monitor the measured variable in relation to a programmable limit.

The normal state of the transmitter is signaled when the green LED (12) is continuously lit. As explained above, it flashes should the measurement sensor become open-circuit. It also flashes, however, if the measured variable falls 10% below the start of the measuring range or rises 10% above its maximum value and during the first five seconds after the transmitter is switched on.

The push-button S1 is for automatically calibrating the leads of a two-wire resistance thermometer circuit. This is done by temporarily shorting the resistance sensor and pressing the button for at

least three seconds. The lead resistance is then automatically measured and taken into account when evaluating the measure variable.

The power supply H is connected to terminals 5 and 10 on the input block (15). The polarity is of no consequence, because the input voltage is chopped on the primary side of the power block (16) before being applied to a full-wave rectifier. Apart from the terminals, the input block (15) also contains an EMC filter which suppresses any electromagnetic interference superimposed on the
power supply. The transformer block (17) provides the electrical insulation between the power supply and the other circuits and also derives two secondary voltages. One of these (5 V) is rectified and stabilized in (18) and then supplies the electronic circuits on the input side of the transmitter. The other AC from block (17) (–16 V / + 18 V) is rectified in (19) and used to supply the relay driver and the other components on the output side of the transmitter.

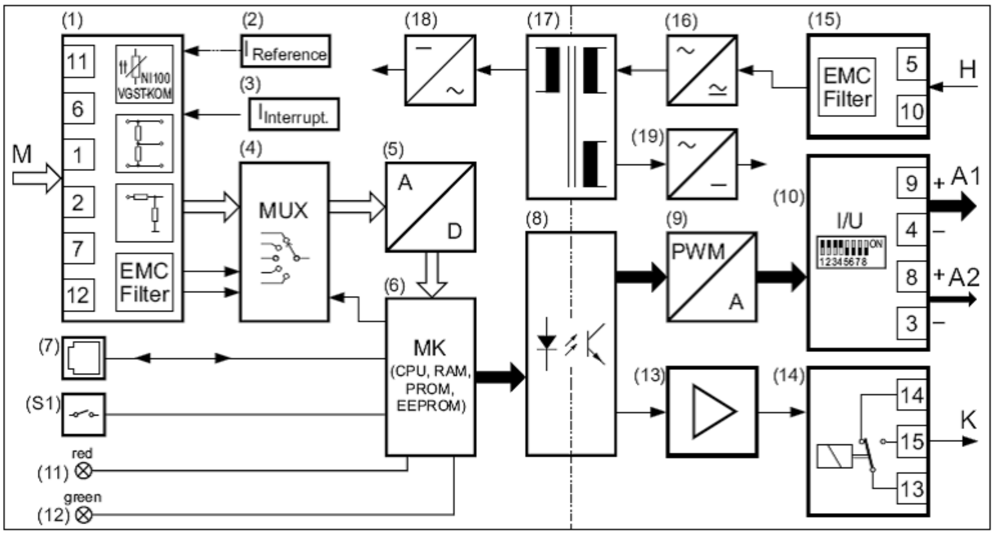


Fig.3. Block diagram. I

Programming (Figs. 4 and 5)

A PC with RS 232 C interface(Windows 3.1x,95,98,NTor 2000),the programming cable PRKAB 600 and the configuration software VC 600 are required to program the transmitter.(Details of the programming cable and the software are to be found in the separate Data sheet:PRKAB 600Le.)

The connections between "PC ⟷ PRKAB 600 ⟷ *RISH*Ducer V 604" can be seen from

Fig. 4. The power supply must be applied to *RISH*Ducer V 604 before it can be programmed.

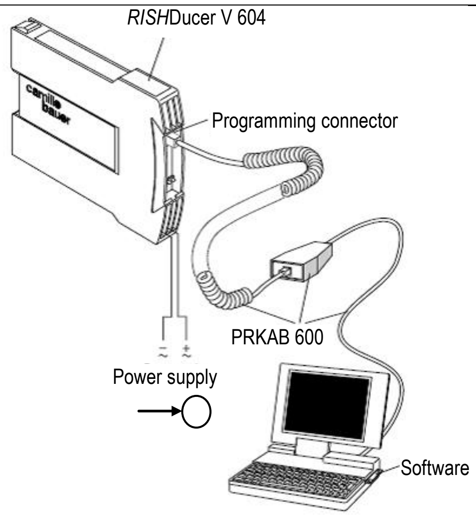


Fig.4

The software VC 600 is supplied on a CD.

The programming cable PRKAB 600 adjusts the signal level and provides the electrical insulation between the PC and *RISH* Ducer V 604.

The programming cable PRKAB 600 is used for programming both standard and Ex versions.

Of the programmable details listed in section “Features / Benefits” one parameter – the output signal – has to be determined by PC programming as well as mechanical setting on the transmitter unit …

… the output signal range by PC

… the type of output (current or voltage signal) has to be set by DIP switch (see Fig. 5).

The eight pole DIP switch is located on the PCB in the *RISH* Ducer V 604

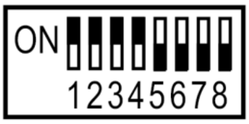
DIP switches	Type of output signal
	Load-independent current
	Load-independent Voltage

Fig.5

Technical ata

Measuring input

Measured variable M
The measured variable M and the measuring range can be Programmed

Table 1: Measured variables and measuring ranges

Measured variables	Measuring ranges		
	Limits	Min. span	Max. span
DC voltages			
direct input	±300 mV[1]	2 mV	300 mV
via potential divider[2]	± 40 V[1]	300 mV	40 V
DC currents			
low current range	± 12 mA[1]	0.08 mA	12 mA
high current range	– 50 to + 100 mA[1]	0.75 mA	100 mA
Temperature monitored by two, three or four-wire resistance thermometers	– 200 to 850°C		
low resistance range	0...740 Ω[1]	8 Ω	740 Ω
high resistance range	0...5000 Ω[1]	40 Ω	5000 Ω
Temperature monitored by thermocouples	– 270 to 1820°C	2 mV	300 mV
Variation of resistance of remote sensors / potentiometers low resistance range	0...740 Ω[1]	8 Ω	740 Ω
high resistance range	0...5000 Ω[1]	40 Ω	5000 Ω

[1] Note permissible value of the ratio “full-scale value/span ≤≤ 20”.

DC voltage

Measuring range: See Table 1
Direct input: Wiring diagram No. 1[1]
Input resistance: Ri > 10 MΩ
Continuous overload max. – 1.5 V,+ 5 V

Input via

potential divider: Wiring diagram No. 2[1]
Input resistance: Ri =1 MΩ Ω Continuous overload ax.±100V

DC current

Measuring range: See Table 1
Low currents: Wiring diagram No. 3[1]
Input resistance: Ri=24.7Ω Continuous overload ax. 150mA
High currents: Wiring diagram No. 3[1]
Input resistance: Ri = 24.7Ω Continuous overload max.150 mA

Resistance thermometer

Measuring range: See Tables 1 and 8
Resistance types: Type Pt 100 (DIN IEC 751)
Type Ni 100 (DIN 43 760)
Type Pt 20/20 °C
Type Cu 10/25°C
Type Cu 20/25°C
See “Table 6: Specification and or dering information”, feature 6 for other Pt or Ni.
Measuring current: ≤0.38 mA for measuring ranges 0..740Ω or
≤0.06 mA for measuringranges0..5000Ω
Standard circuit: 1 resistance thermometer:
– two-wire connection, wiring diagram No. 4[1]
– three-wire connection, wiring diagram No. 5[1]
– four-wire connection, wiring diagram No. 6[1]
Summation circuit: Series or parallel connection of 2 or more two, three or four-wire resistance thermometers for deriving the mean temperature or for matching other types of sensors,wiring diagram nos. 4-6[1]
Differential circuit: 2 identical three-wire resistance thermometers for deriving the mean temperature RT1–RT2, wiring diagram No. 7[1]
Input resistance: R_i> 10 M Ω
Lead resistance: ≤ 30 Ω per lead

Thermocouples

Measuring range: See Tables 1 and 8
Thermocouple pairs: Type B:Pt30Rh-Pt6Rh (IEC 584)
Type E: NiCr-CuNi (IEC 584)
Type J: Fe-CuNi (IEC 584)
Type K:NiCr-Ni (IEC 584)
Type L: Fe-CuNi (DIN 43710)
Type N:NiCrSi-NiSi (IEC 584)
Type R:Pt13Rh-Pt (IEC 584)
Type S: Pt10Rh-Pt (IEC 584)
Type T: Cu-CuNi (IEC 584)
Type U:Cu-CuNi (DIN 43710)
Type W5-W26 Re
Other thermocouple pairs on request
Standard circuit: 1 thermocouple, internal cold junction compensation, wiring diagram No. 8[1]
1 thermocouple, external cold junction compensation, wiring diagram No. 9[1]
Summation circuit: 2or more thermocouples in a summation circuit for deriving the mean temperature,external cold junction compensation, wiring diagram No. 10[1]
Differential circuit: 2 identical thermocouples in a differential circuit for deriving the mean temperature TC1 – TC2, no provision for cold junction compensation, wiring diagram No. 11[1]
Input resistance: R_i > 10 M Ω

Cold junction

compensation: Internal or external
Internal: Incorporated Ni 100
Permissible variation of the internal cold junction compensation: ± 0.5 K at 23 °C, ± 0.25 K/10 K
External: 0...70°C, programmable

[1] See “Table 9: Measuring input”.

Resistance sensor, potentiometer

Measuring range:	See Table 1
Resistance sensor types:	Type WF Type WF DIN Potentiometer see "Table 6: specification and ordering information "feature 5.
Measuring current:	≤≤0.38 mA for measuring range 0..740Ω Ωor ≤≤ 0.06 mA for measuring range 0..5000Ω
Kinds of input:	1 resistance sensor WF current measured at pick-up, wiring diagram No. 12[1] 1 resistance sensor WF DIN current measured at pick-up, wiring diagram No. 13[1] 1 resistance sensor for two, three or four-wire connection, wiring diagram No. 4-6[1] 2 identical three-wire resistance sensors for deriving a differential, wiring diagram No.7[1]
Input resistance:	R_i > 10 M
Lead resistance:	≤30 Ω Ωper lead

Output signal

Output signals A1 and A2

The output signals available at A1and A2 can be configured for either an impressed DC current $_A$ I or a superimposed DC voltage U_A by appropriately setting DIP switches. The desired range is programmed using a PC. A1 and A2 are not DC isolated and exhibit the same value.

Standard ranges for I $_A$:	0...20 mA or 4...20 mA
Non-standard ranges:	Limits –22 to + 22 mA Min. span 5 mA Max. span 40 mA
Open-circuit voltage:	Neg. –13.2...–18 V, pos. 16.5...21 V
Burden voltage I_{A1}:	+ 15 V, resp. –12 V
External resistance I_{A1}:	R_{ext} max. [k Ω] = $\frac{15\ V}{I_{AN}\ [mA]}$ resp. = $\frac{-12\ V}{I_{AN}\ [mA]}$ I_{AN} = full-scale output current
Burden voltage I_{A2}:	< 0.3 V
External resistance I_{A2} :	R_{ext} max. [k Ω] = $\frac{0{,}3\ V}{I_{AN}\ [mA]}$
Residual ripple:	< 1% p.p., DC ... 10 kHz < 1.5% p.p. for an output span < 10 mA
Standard ranges for U_A :	0...5, 1...5, 0...10 or 2...10 V
Non-standard ranges:	Limits –12 to + 15 V Min. span 4 V Max. span 27 V
Open-circuit voltage:	≤ 40 mA
Load capacity U_{A1} / U_{A2}	20 mA
External resistance U_{A1} / U_{A2}:	R_{ext} [k Ω] ≥ $\frac{U_A\ [V]}{20\ mA}$
Residual ripple:	< 1% p.p., DC ... 10 kHz < 1,5% p.p. for an output span < 8 V

[1] see "Table 9: Measuring input"
[2] In relation to analogue output span A1 resp.A2.

Fixed settings for the output signals A1 and A2

After switching on:	A1 and A2 are at a fixed value for 5 s after switching on(default).Setting range –10 to 110%[2] programmable, e.g. between 2.4 and 21.6 mA (for a scale of 4 to 20 mA). The green LED ON flashes for the 5 s
When input variable out of limits:	A1 and A2 are at either a lower or an upper fixed value when the input variable…… … falls more than10% below the minimum value of the permissible range … exceeds the maximum value of the permissible range by more than 10%. Lower fixed value = –10%[2], e.g. –2 mA (for a scale of 0 to 20 mA). Upper fixed value = 110%[2], e.g. 22 mA (for a scale of 0 to 20 mA). The green LED ON flashes
Open-circuit sensor:	A1 and A2 are at a fixed value when an open-circuit sensor is detected (see Section "Sensor and open-circuit lead supervision"). The fixed value of A1 and A2 is configured to either maintain their values at the instant the open-circuit occurs or adopt a preset value between –10 and 110%[2] ,e.g. between 1.2 and 10.8 V (for a scale of 2 to 10 V). The green LED ON flashes and the red LED lights continuously

Power supply H

DC, AC power pack (DC and 45...400 Hz)

Table 3: Nominal voltage and tolerance

Nominal voltage U_N	Tolerance
24... 60 V DC / AC	DC –15...+ 33% AC ± 15%
85...230 V [3] DC / AC	

Power consumption: ≤ 1.4 W resp.≤ 2.7 VA

Open-circuit sensor circuit supervision

Resistance thermometers, thermocouples, remote sensors and potentiometer input circuits are supervised. The circuits of DC voltage and current inputs are not supervised

Pick-up/reset level:	1 to 15 k Ω acc. to kind of measure men and range

Signaling modes

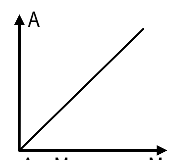
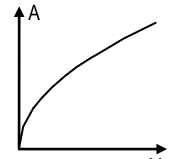
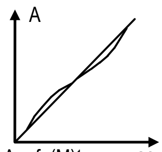
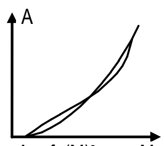
Output signals A1 and A2:	Programmable fixed values. The fixed value of A1 and A2 is configured to either maintain their values at the instant the open-circuit occurs or adopt a preset value between – 10 and 110%[4] , e.g. between 1.2 and 10.8 V (for a scale of 2 to 10 V)
Front plate signals:	The green LED ON flashes and the red LED lights continuously
Output contact K:	Relay 1 potentially-free changeover contact (see Table 4) Operating sense programmable The relay can be either energized or de-energized in the case of a disturbance. Set to "Relay inactive" if not required!

[2] *25 input points M given referred to a quadratic output scale from –10% to + 110%. Pre-defined output points: 0, 0, 0, 0.25, 1, 2.25, 4.00, 6.25, 9.00, 12.25, 16.00, 20.25, 25.00, 30.25, 36.00, 42.25, 49.00, 56.25, 64.00, 72.25, 81.00, 90.25, 100.0, 110.0, 110.0%.*
[3] *An external supply fuse must be provided for DC supply voltages> 125 V.*
[4] *In relation to analogue output span A1 resp. A2.*

Output characteristic

Characteristic: Programmable

Table 2: Available characteristics (acc. to measured variable)

Measured variables	Characteristic	
DC voltage		
DC current		
Resistance thermometer (linear variation of resistance)		
Thermocouple (linear variation of voltage)		
Sensor or potentiometer	A = M M	
DC voltage		
DC current	$A = \sqrt{M}$ or $A = \sqrt{M^3}$ M	
DC voltage		Special characteristics
DC current		
Resistance thermometer (linear variation with temperature)		
Thermocouple signal (linear variation with temperature)	A = f (M)[1] M	
Sensor or potentiometer	linearised	
DC voltage		
DC current		
Sensor or potentiometer	A = f (M)[2] M quadratic	

Operating sense: Programmable output signal directly or inversely proportional to measured variable

Setting time (IEC 770): Programmable from 2 to 30 s

Supervising a limit GW (⎍)

This Section only applies to transmitters which are not configured to use the output contact K in conjunction with the open-circuit sensor supervision (see Section "Open-circuit sensor circuit supervision").

This applies ...

... in all cases when the measured variable is a DC voltage or current

... when the measured variable is a resistance thermometer, a thermocouple, a remote sensor or a potentiometer and the relay is set to "Relay disabled"

Limit: Programmable
– Disabled
– Lower limit value of the measured variable (see Fig. 6, left)
– Upper limit value of the measured variable (see Fig. 6, right)
– Maximum rate of change of the measured variable measured variable

$$\text{Slope} = \frac{\Delta \text{ measured variable}}{\Delta t}$$

(see Fig. 6, right)

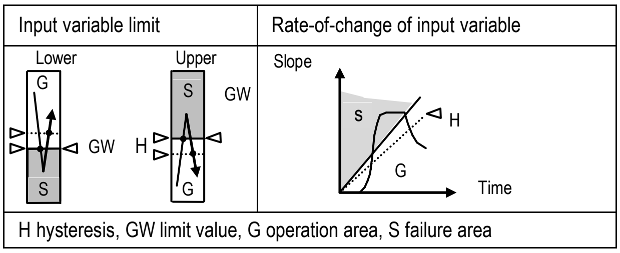


Fig. 6. Switching function according to limit monitored.

Trip point setting using PC for GW: Programmable
– between –10 and 110%[1] (of the measured variable)
– between ± 1 and ± 50% [1]/s (of the rate-of-change of the measured variable)

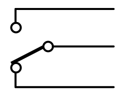
Reset ratio: Programmable
– between 0.5 and 100%[1] (of the measured variable)
– between 1 and 100%[1]/s (of the rate-of-change of the measured variable)

Operating and resetting delays: Programmable
– between 1 to 60 s

Operating sense: Programmable
– Relay energized, LED on
– Relay energized, LED off
– Relay de-energized, LED on
– Relay de-energized, LED off
(once limit reached)

Relay status signal: GW by red LED (⎍)

Table 4: Contact arrangement and data

Symbol	Material	Contact rating
	Gold flashed silver alloy	AC: ≤ 2 A / 250 V (500 VA) DC: ≤ 1 A / 0.1…250 V (30 W)

Relay approved by UL, CSA, TÜV, SEV

Programming connector

Interface: RS 232 C
FCC-68 socket: 6/6 pin
Signal level: TTL (0/5 V)
Power consumption: Approx. 50 mW

Accuracy data (acc. to DIN/IEC 770)

Basic accuracy: Max. error ≤ + 0.2%
Including linearity and repeatability errors for current, voltage and resistance measurement

Additional error (additive):
< ± 0.3%for linearised characteristic
< ± 0.3% for measuring ranges < 5 mV, 0.3…0.75 V, < 0.2 mA or < 20 Ω
< ± 0.3% for a high ratio between full-scale value and measuring range > factor 10, e.g. Pt 100 175.84 …194.07 Ω ≙ 200 0°C…250°C
< ± 0.3% for current output < 10 mA span
< ± 0.3% for voltage output < 8 V span
< 2 · (basic and additional error) for two-wire resistance measurement

Reference conditions:
Ambient temperature: 23 0°C, ± 2 K
Power supply: 24 V DC ± 10% and 230 V AC ± 10%
Output burden: Current: 0.5 · R_{ext} max.
Voltage: 2 · R_{ext} min.

Influencing factors:
< ± 0.1 … 0.15% per 10 K
Temperature: < ± 0.1% for current output
Burden: < 0.2% for voltage output, providing R_{ext} > 2 · R_{ext} min.

Long-time drift: < ± 0.3% / 12 months
Switch-on drift: < ± 0.5%

Common and transverse mode influence: <± 0.2%
+ or – output connected to ground: < ± 0.2%

Installation ata

Housing: Housing typeS17 Refer to Section "Dimensional draw drawings" for dimensions

Material of housing: Lexan 940 (polycarbonate). Flammability Class V-0 acc. to UL 94,self-extinguishing, non-dripping, free of halogen

Mounting: For snapping onto top-hat rail (35 x15 mm or 35 x 7.5 mm) acc. to EN 50 022 or directly onto a wall or panel using the pull-out screw hole brackets

Mounting position: Any

Terminals: DIN/VDE 0609 Screw terminals with wire guards for light PVC wiring and max. 2 x0.75 mm2 or 1 x 2,5 mm^2

Permissible vibrations: 2 g acc. to EN 60 068-2-6
10 … 150 … 10 Hz 10 cycles

Choc: 3 x50 g 3 shocks each in 6 directions acc. to EN 60 068-2-27

Weight: Approx. 0.25 kg

Electrical insulation: All circuits (measuring input/measuring outputs/power supply/output contact) are electrically insulated. Programming connector and measuring input are connected. The PC is electrically insulated by the programming cable PRKAB 600.

Stan ar s

Electromagnetic compatibility: The standards DIN EN 50 081-2 and DIN EN 50 082-2 are observed

Intrinsically safe: Acc. to DIN EN 50 020: 1996-04

Protection (acc. to IEC 529 resp. EN 60 529): Housing IP 40 Terminals IP 20

Electrical design: Acc. to IEC 1010 resp. EN 61 010

Operating voltages: Measuring input < 40 V Programming connector, measuring outputs < 25 V
Output contact, power supply < 250 V

Rated insulation voltages: Measuring input, programming connector, measuring outputs, output contact, power supply < 250 V

Pollution degree: 2

Installation category II: Measuring input, programming connector, measuring outputs, output contact

Installation category III: Power supply

Test voltages: Measuring input and programming connector to:
– Measuring outputs 2.3 kV, 50 Hz, 1min.
– Power supply 3.7 kV, 50 Hz, 1 min.
– Output contact 2.3 kV, 50 Hz, 1 min.
Measuring outputs to:
– Power supply 3.7 kV, 50 Hz, 1 min.
– Output contact 2.3 kV, 50 Hz, 1 min.
Serial interface for the PC to:
– everything else 4 kV, 50 Hz, 1 min. (PRKAB 600)

Ambient con itions

Commissioning temperature: – 10 to + 55 °C

Operating temperature: – 25 to + 55°C, Ex – 20 to + 55°C

Storage temperature: – 40 to + 70°C

Relative humidity annual mean: ≤ 75% standard climatic rating
≤ 95% enhanced climatic rating

Basic configuration:

Measuring input 0…5 V DC
Measuring output 0…20 mA linear, fixed value 0%
during 5 s after switching on Setting time 0.7 s Open-circuit supervision inactive Mains ripple suppression 50 Hz
Limit functions inactive

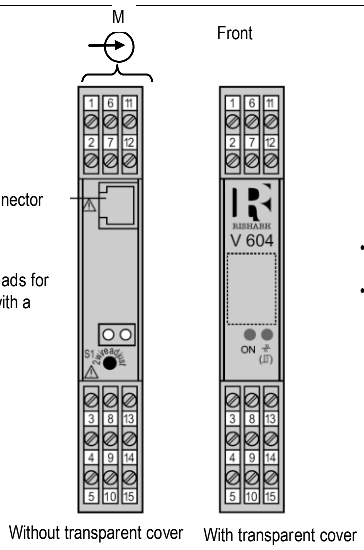
Basic configuration

The transmitter *RISH* Ducer V 604 is also available already program-med with a basic configuration which is especially recommended In cases where the programming data is not known at the time Of ordering (see "Table 6: Specification and ordering information" Feature 4.)*RISH* Ducer V 604 supplied as standard versions are programmed For basic configuration (see "Table 5: Standard versions").

Table 5: Standard versions

The following 8 transmitter versions are already programmed for basic configuration and are available as standard versions. It is necessary to quote the Order No.:

Cold junction compensation	Climatic rating	Instrument	Power supply
			24… 60 V DC / AC
Included	standard	Standard version	85…230 V DC /AC



M = Measured variable / measuring input, Terminal allocation acc. to the measuring mode and application see "Table 9: Measuring input"
A1 = Output signal / measuring output
A2 = 2nd output (field indicator) (Only brief use permitted in the case of the Ex version)
K = Output contact for open-circuit sensor supervision or for monitoring a limit GW
H = Power supply

• ON Green LED for indicating device standing by
• Red LED for indicating operation of open-circuit or trip point GW (where a limit monitor is ordered instead of the open-circuit sensor supervision)